

EPOS4 EtherCAT Card

Hardware Reference







EPOS4 EtherCAT Card Positioning Controller | P/N 581245 Hardware Reference CCMC | Edition 2019-11 | DocID rel8613



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READ THIS FIRST

These instructions are intended for qualified technical personnel. Prior commencing with any activities...

- you must carefully read and understand this manual and
- you must follow the instructions given therein.

1 ABOUT

1.1 About this Document

1.1.1 Intended Purpose

Use the document to... --stay safe, --be fast, --end up with set up and ready-togo equipment. The purpose of the present document is to familiarize you with the EPOS4 EtherCAT Card. It will highlight the tasks for safe and adequate installation and/or commissioning. Follow the described instructions ...

- to avoid dangerous situations,
- to keep installation and/or commissioning time at a minimum,
- to increase reliability and service life of the described equipment.

The present document is part of a documentation set and contains performance data and specifications, information on fulfilled standards, details on connections and pin assignment, and wiring examples. The below overview shows the documentation hierarchy and the interrelationship of its individual parts:



Figure 1-1 Documentation structure

1.1.2 Target Audience

The present document is intended for trained and skilled personnel. It conveys information on how to understand and fulfill the respective work and duties.

1.1.3 How to use

Throughout the document, the following notations and codes will be used.

Notation	Meaning
Module	refers to an EPOS4 Module (such as «EPOS4 Module 24/1.5», «EPOS4 Module 50/15», and others)
(n)	refers to an item (such as part numbers, list items, etc.)
→	denotes "see", "see also", "take note of" or "go to"

Table 1-1 Notation used

1.1.4 Symbols & Signs

In the course of the present document, the following symbols and signs will be used.

Туре	Symbol	Meaning			
	(typical)	DANGER	Indicates an imminent hazardous situation . If not avoided, it will result in death or serious injury .		
Safety alert		WARNING	Indicates a potential hazardous situation . If not avoided, it can result in death or serious injury .		
		CAUTION	Indicates a probable hazardous situation or calls the attention to unsafe practices. If not avoided, it may result in injury .		
Prohibited action		Indicates a dangerous action. Hence, you must not !			
	(typical)				
Mandatory action	(typical)	Indicates a mandatory action. Hence, you must !			
		Indicates an activity you must perform prior continuing, or gives information on a particular item you need to observe.			
Information	9	Best practice	Indicates an advice or recommendation on the easiest and best way to further proceed.		
	**	Material Damage	Indicates information particular to possible damage of the equipment.		

Table 1-2 Symbols and signs

1.1.5 Trademarks and Brand Names

For easier legibility, registered brand names are listed below and will not be further tagged with their respective trademark. It must be understood that the brands (the list below is not necessarily concluding) are protected by copyright and/or other intellectual property rights even if their legal trademarks are omitted in the later course of this document.

Brand name	Trademark owner
Adobe® Reader® © Adobe Systems Incorporated, USA-San Jose, CA	
EtherCAT®	$^{\odot}$ EtherCAT Technology Group, DE-Nuremberg, licensed by Beckhoff Automation GmbH, DE-Verl
PCI Express® PCIe®	© PCI-SIG, USA-Beaverton, OR
Windows®	© Microsoft Corporation, USA-Redmond, WA

Table 1-3Brand names and trademark owners

1.1.6 Copyright

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1.2 About the Device

Capabilities of the device, included features, and supported controllers.

maxon's «EPOS4 EtherCAT Card» is a plug-in extension card to provide complete EtherCAT communication capability for an EPOS4 positioning controller. It is optionally available to equip either an EPOS4 encased housing variant or an EPOS4 Module with full EtherCAT functionality. For the latter, development of an own motherboard as to particular guidelines is needed (for details →chapter "4 Motherboard Design Guide" on page 4-17).



Find the latest edition of the present document as well as additional documentation and software for EPOS4 positioning controllers also on the Internet: →http://epos.maxongroup.com

In addition, you may wish to browse the EPOS video library. It features video tutorials that provide easy to follow instructions on how to get started with «EPOS Studio» and shows you tips and tricks on how to setup communication interfaces, and so on. Explore on Vimeo: →https://vimeo.com/album/4646388



1.3 About the Safety Precautions

Keep in mind: Safety first! Always!

- Make sure that you have read and understood the note "READ THIS FIRST" on page A-2!
- Do not engage with any work unless you possess the stated skills (→ chapter "1.1.2 Target Audience" on page 1-3)!
- Refer to →chapter "1.1.4 Symbols & Signs" on page 1-4 to understand the subsequently used indicators!
- You must observe any regulation applicable in the country and/or at the site of implementation with regard to health and safety/accident prevention and/or environmental protection!



DANGER

High voltage and/or electrical shock

Touching live wires causes death or serious injuries!

- Consider any power cable as connected to live power, unless having proven the opposite!
- · Make sure that neither end of cable is connected to live power!
- Make sure that power source cannot be engaged while work is in process!
- Obey lock-out/tag-out procedures!
- Make sure to securely lock any power engaging equipment against unintentional engagement and tag it with your name!



Requirements

- Make sure that all associated devices and components are installed according to local regulations.
- Be aware that, by principle, an electronic apparatus cannot be considered fail-safe. Therefore, you must
 make sure that any machine/apparatus has been fitted with independent monitoring and safety equipment. If the machine/apparatus should break down, if it is operated incorrectly, if the control unit breaks
 down or if the cables break or get disconnected, etc., the complete drive system must return and be
 kept in a safe operating mode.
- Be aware that you are not entitled to perform any repair on components supplied by maxon.



Electrostatic sensitive device (ESD)

- Wear working cloth and use equipment in compliance with ESD protective measures.
- Handle device with extra care.



Hot plugging/hot swapping the card may cause hardware damage

Switch off the controller's power supply before removing or inserting an extension card.

2 SPECIFICATIONS

2.1 Technical Data

	EPOS4 EtherCAT Card (581245)				
Electrical	Nominal power s	upply voltage +V _{cc}	1070 VDC		
Rating	Absolute supply	voltage + V_{min} / + V_{max}	8 VDC / 76 VDC		
Interface	EtherCAT input EtherCAT output		As to IEEE 802.3 100 Base T		
	Max. bit rate		100 Mbit/s (full duplex)		
	Weight		approx. 7 g		
Physical	Dimensions (L x	W x H)	41 x 25 x 9.2 mm		
	Mounting		Card edge connector, PCIe; 2x18 position		
	Temperature	Operation	−30…+60 °C		
		Extended range (1)	For details consult Hardware Reference of respective EPOS4 controller		
Environment		Storage	−40…+85 °C		
	Altitude (2)	Operation	010'000 m MSL		
	Humidity		590% (condensation not permitted)		

- (1) Operation within the extended range is permitted. However, a respective derating (declination of output current I_{cont}) as to the stated values will apply.
- (2) Operating altitude in meters above Mean Sea Level, MSL.

Table 2-4 Technical data



2.2 Dimensional Drawings



Figure 2-2 EPOS4 EtherCAT Card with card edge connector & retainer – Dimensional drawing [mm]



2.3 Standards

The described device has been successfully tested for compliance with the below listed standards. In practical terms, only the complete system (the fully operational equipment comprising all individual components, such as motor, servo controller, power supply unit, EMC filter, cabling etc.) can undergo an EMC test to ensure interference-free operation.



Important notice

The device's compliance with the mentioned standards does not imply its compliance within the final, ready to operate setup. In order to achieve compliance of your operational system, you must perform EMC testing of the involved equipment as a whole.

	Electromagnetic Compatibility				
	IEC/EN 61000-6-2	Immunity for industrial environments			
Generic	IEC/EN 61000-6-3	Emission standard for residential, commercial and light- industrial environments			
	IEC/EN 55022 (CISPR22)	Radio disturbance characteristics / radio interference			
Applied	IEC/EN 61000-4-3	Radiated, radio-frequency, electromagnetic field immunity test >10 V/m			
	IEC/EN 61000-4-4	Electrical fast transient/burst immunity test ±2 kV			
	IEC/EN 61000-4-6	Immunity to conducted disturbances, induced by radio- frequency fields 10 Vrms			

	Others				
Environment	IEC/EN 60068-2-6	Environmental testing – Test Fc: Vibration (sinusoidal, 10500 Hz, 20 m/s²)			
	MIL-STD-810F	Random transport (10…500 Hz up to 2.53 g_{rms})			
Safety	UL File Number	Unassembled printed circuit board: E207844			
Reliability	MIL-HDBK-217F	Reliability prediction of electronic equipment Environment: Ground, benign (GB) Ambient temperature: 298 K (25 °C) Component stress: In accordance with circuit diagram and nominal power Mean Time Between Failures (MTBF) 544'021 hours			

Table 2-5 Standards



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3 SETUP

3.1 Generally applicable Rules



Maximal permitted supply voltage

• Make sure that supply power is between 10...70 VDC.

• Supply voltages above 76 VDC, or wrong polarity will destroy the unit.



Hot plugging/hot swapping the card may cause hardware damage Switch off the controller's power supply before removing or inserting an extension card.

3.2 Connections



PinSignalDescriptionPinSignalDescriptionA1-Connect to EtherCAT OUT X15 4B1TX+_OUTEtherCAT OUT Transmission Data+A2-Connect to EtherCAT OUT X15 5B2TXOUTEtherCAT OUT Transmission Data-A3-Connect to EtherCAT OUT X15 7B3RX+_OUTEtherCAT OUT Receive Data+A4-Connect to EtherCAT OUT X15 8B4RXOUTEtherCAT OUT Receive Data+A5-Connect to EtherCAT IN X14 4B5TX+_INEtherCAT IN Transmission Data+A6-Connect to EtherCAT IN X14 5B6TXINEtherCAT IN Transmission Data+A7-Connect to EtherCAT IN X14 5B7RX+_INEtherCAT IN Receive Data+A8-Connect to EtherCAT IN X14 5B7RX+_INEtherCAT IN Receive Data+A8-Connect to EtherCAT IN X14 7B7RX+_INEtherCAT IN Receive Data+A9LED_EtherCAT_OUTLink activity of port EtherCAT IN X14 8B8RXINEtherCAT IN Receive Data+A9LED_EtherCAT_OUTLink activity of port EtherCAT OUT X15 8B9LED_EtherCAT_INEtherCAT IN X14A10-not connectedB10-not connectedA11A11LED_Status_redEtherCAT status "Error"B11LED_Status_greenEtherCAT in X14A13GNDGroundB13SPL_SIMOSPI Slave input/Master out			ray			ray 3
A1-EtherCAT OUT X15 [4B1IX+_OUTTransmission Data+A2-Connect to EtherCAT OUT X15 [5B2TXOUTEtherCAT OUT Transmission Data-A3-Connect to EtherCAT OUT X15 [7B3RX+_OUTEtherCAT OUT 	Pin	Signal	Description	Pin	Signal	Description
A2-EtherCAT OUT X16 5B2IXOUTTransmission Data-A3-Connect to EtherCAT OUT X15 7B3RX+_OUTEtherCAT OUT Receive Data-A4-Connect to EtherCAT OUT X15 8B4RXOUTEtherCAT OUT Receive Data-A5-Connect to EtherCAT IN X14 4B5TX+_INEtherCAT IN Transmission Data+A6-Connect to EtherCAT IN X14 5B6TXINEtherCAT IN Transmission Data+A7-Connect to EtherCAT IN X14 5B6TXINEtherCAT IN Transmission Data+A8-Connect to EtherCAT IN X14 7B7RX+_INEtherCAT IN Receive Data+A8-Connect to EtherCAT IN X14 7B7RX+_INEtherCAT IN Receive Data+A9LED_EtherCAT_OUTLink activity of port EtherCAT OUT X15B9LED_EtherCAT_IN Link activity of portA10-not connectedB10-not connectedA11LED_Status_redEtherCAT status "Error"B11LED_Status_greenEtherCAT status "Run"A13GNDGroundB14SPI_SIMOSPI Slave input/Master outputA14GNDGroundB14SPI_CS2SPI chip select 2A16-not connectedB15SPI_CS2SPI chip select 2A16A17MDGroundB16SPI_IRQSPI interrupt requestA18A14Nominal power supply voltageB16SPI_IRQSPI interr	A1	-		B1	TX+_OUT	
A3-EtherCAT OUT X15 [7B3RX+_OU1Receive Data+A4-Connect to EtherCAT OUT X15 [8B4RX+_OUTEtherCAT OUT Receive Data-A5-Connect to EtherCAT IN X14 [4B5TX+_INEtherCAT IN Transmission Data+A6-Connect to EtherCAT IN X14 [5B6TX+_INEtherCAT IN Transmission Data+A7-Connect to EtherCAT IN X14 [7B7RX+_INEtherCAT IN Transmission Data-A8-Connect to EtherCAT IN X14 [7B7RX+_INEtherCAT IN Receive Data+A8-Connect to EtherCAT IN X14 [7B7RX+_INEtherCAT IN Receive Data+A9LED_EtherCAT_OUTLink activity of port EtherCAT IN X14 [8B8RXINEtherCAT IN X14A10-not connectedB10-not connectedA11LED_Status_redEtherCAT status "Error"B11LED_Status_greenEtherCAT status "Run"A12ShieldCable shieldB12SPI_SOMISPI Slave output/Master outputA13GNDGroundB14SPI_SIMOSPI Slave input/Master outputA14GNDGroundB16SPI_CS2SPI chip select 2A16-not connectedB16SPI_IRQSPI interrupt requestA14GNDGroundB16SPI_IRQSPI interrupt requestA15-not connectedB16SPI_IRQSPI interrupt requestA16AND <td< td=""><td>A2</td><td>-</td><td></td><td>B2</td><td>TXOUT</td><td></td></td<>	A2	-		B2	TXOUT	
A4-EtherCAT OUT X15 8B4FXOUTReceive Data-A5-Connect to EtherCAT IN X14 4B5TX+_INEtherCAT IN Transmission Data+A6-Connect to EtherCAT IN X14 5B6TXINEtherCAT IN Transmission Data-A7-Connect to EtherCAT IN X14 7B7RX+_INEtherCAT IN Receive Data+A8-Connect to EtherCAT IN X14 7B7RX+_INEtherCAT IN Receive Data+A9LED_EtherCAT_OUTLink activity of port EtherCAT OUT X15 8B8RXINEtherCAT IN X14A10-not connectedB10-not connectedA11LED_Status_redEtherCAT status "Error"B11LED_Status_greenEtherCAT status "Run"A12ShieldCable shieldB12SPI_SOMISPI Slave output/Master outputA13GNDGroundB14SPI_CLKSPI clockA14GNDGroundB15SPI_CS2SPI clockA15-not connectedB16SPI_IRQSPI interrupt requestA16A/VNominal power supply voltageB18accore active a	A3	-		B3	RX+_OUT	
A5-EtherCAT IN X14 4B5IX+_INTransmission Data+A6-Connect to EtherCAT IN X14 5B6TXINEtherCAT IN Transmission Data-A7-Connect to EtherCAT IN X14 7B7RX+_INEtherCAT IN Receive Data+A8-Connect to EtherCAT IN X14 8B8RXINEtherCAT IN Receive Data+A9LED_EtherCAT_OUTLink activity of port EtherCAT IN X14 8B9LED_EtherCAT_IN EtherCAT IN X14A10-not connectedB10-not connectedA11LED_Status_redEtherCAT status "Error"B11LED_Status_greenEtherCAT status "Run"A12ShieldCable shieldB12SPI_SOMISPI Slave output/Master inputA13GNDGroundB14SPI_CLKSPI clockA14GNDInt connectedB15SPI_CS2SPI clockA15-not connectedB16SPI_LRQSPI interrupt requestA16AMOMinal power supply voltageB18and connected	A4	-		B4	RXOUT	
A6-EtherCAT IN X14 5B6IXINTransmission Data-A7-Connect to EtherCAT IN X14 7B7RX+_INEtherCAT IN Receive Data+A8-Connect to EtherCAT_IN X14 8B8RXINEtherCAT IN Receive Data-A9LED_EtherCAT_OUTLink activity of port EtherCAT OUT X15B9LED_EtherCAT_IN EtherCAT_IN X14A10-not connectedB10-not connectedA11LED_Status_redEtherCAT status "Error"B11LED_Status_greenEtherCAT status "Run"A12ShieldCable shieldB12SPI_SOMISPI Slave output/Master inputA13GNDGroundB14SPI_CLKSPI clockA14GNDGroundB16SPI_CS2SPI chip select 2A16-not connectedB16SPI_IRQSPI interrupt requestA18t/vNominal power supply voltageB18-not connected	A5	-		B5	TX+_IN	
A7-EtherCAT IN X14 7B7RX+_INReceive Data+A8-Connect to EtherCAT IN X14 8B8RXINEtherCAT IN Receive Data-A9LED_EtherCAT_OUTLink activity of port EtherCAT OUT X15B9LED_EtherCAT_INLink activity of port EtherCAT IN X14A10-not connectedB10-not connectedA11LED_Status_redEtherCAT status "Error"B11LED_Status_greenEtherCAT status "Run"A12ShieldCable shieldB12SPI_SOMISPI Slave output/Master inputA13GNDGroundB13SPI_SIMOSPI slave input/Master outputA14GNDGroundB15SPI_CS2SPI clockA15-not connectedB16SPI_IRQSPI interrupt requestA17GNDGroundB17-not connectedA18±VNominal power supply voltageB18ant connected	A6	-		B6	TXIN	
A8-EtherCAT IN X14 8B8RXINReceive Data-A9LED_EtherCAT_OUTLink activity of port EtherCAT OUT X15B9LED_EtherCAT_INLink activity of port EtherCAT IN X14A10-not connectedB10-not connectedA11LED_Status_redEtherCAT status "Error"B11LED_Status_greenEtherCAT status "Run"A12ShieldCable shieldB12SPI_SOMISPI Slave output/Master inputA13GNDGroundB14SPI_CLKSPI clockA14GNDGroundB15SPI_CS2SPI clockA15-not connectedB16SPI_IRQSPI interrupt requestA17GNDGroundB17-not connectedA18±VNominal power supply voltageB18ant connected	A7	-		B7	RX+_IN	
A9LED_EulerCAT_OUTEtherCAT OUT X15B9LED_EulerCAT_INEtherCAT iN X14A10-not connectedB10-not connectedA11LED_Status_redEtherCAT status "Error"B11LED_Status_greenEtherCAT status "Run"A12ShieldCable shieldB12SPI_SOMISPI Slave output/Master inputA13GNDGroundB13SPI_SIMOSPI Slave input/Master outputA14GNDGroundB14SPI_CLKSPI clockA15-not connectedB15SPI_CS2SPI chip select 2A16-not connectedB17-not connectedA17GNDGroundB17-not connectedA18t/vNominal power supply voltageB18-not connected	A8	-		B8	RXIN	-
A11LED_Status_redEtherCAT status "Error"B11LED_Status_greenEtherCAT status "Run"A12ShieldCable shieldB12SPI_SOMISPI Slave output/Master inputA13GNDGroundB13SPI_SIMOSPI Slave input/Master outputA14GNDGroundB14SPI_CLKSPI clockA15-not connectedB15SPI_CS2SPI chip select 2A16-not connectedB17-not connectedA17GNDGroundB17-not connectedA18t/vNominal power supply voltageB18-not connected	A9	LED_EtherCAT_OUT		B9	LED_EtherCAT_IN	
A12ShieldCable shieldB12SPI_SOMISPI Slave output/Master inputA13GNDGroundB13SPI_SIMOSPI Slave input/Master outputA14GNDGroundB14SPI_CLKSPI clockA15-not connectedB15SPI_CS2SPI chip select 2A16-not connectedB16SPI_IRQSPI interrupt requestA17GNDGroundB17-not connected	A10	-	not connected	B10	-	not connected
A13GNDGroundB13SPI_SIMOSPI Slave input/Master outputA14GNDGroundB14SPI_CLKSPI clockA15-not connectedB15SPI_CS2SPI chip select 2A16-not connectedB16SPI_IRQSPI interrupt requestA17GNDGroundB17-not connected	A11	LED_Status_red	EtherCAT status "Error"	B11	LED_Status_green	EtherCAT status "Run"
A14GNDGroundB14SPI_CLKSPI clockA15-not connectedB15SPI_CS2SPI chip select 2A16-not connectedB16SPI_IRQSPI interrupt requestA17GNDGroundB17-not connectedA18+VNominal power supply voltageB18-not connected	A12	Shield	Cable shield	B12	SPI_SOMI	SPI Slave output/Master input
A15-not connectedB15SPI_CS2SPI chip select 2A16-not connectedB16SPI_IRQSPI interrupt requestA17GNDGroundB17-not connectedA18tVNominal power supply voltageB18-not connected	A13	GND	Ground	B13	SPI_SIMO	SPI Slave input/Master output
A16 - not connected B16 SPI_IRQ SPI interrupt request A17 GND Ground B17 - not connected not connected A18 tV Nominal power supply voltage B18 - not connected	A14	GND	Ground	B14	SPI_CLK	SPI clock
A17 GND Ground B17 – not connected	A15	-	not connected	B15	SPI_CS2	SPI chip select 2
A18 +V Nominal power supply voltage B18 not connected	A16	-	not connected	B16	SPI_IRQ	SPI interrupt request
	A17	GND	Ground	B17	-	not connected
	A18	+V _{cc}		B18	-	not connected

Table 3-6

Connector arrays - Pin assignment



3.3 Installation

The procedure varies depending on the type of controller you are using:

- · EPOS4 controllers with encased housing feature two ready-to-use extension slots.
- EPOS4 **Modules** require a custom-made motherboard (for details on design and layout → chapter "4 Motherboard Design Guide" on page 4-17) with a PCIe card edge connector.



Hot plugging/hot swapping the card may cause hardware damage

Switch off the controller's power supply before removing or inserting an extension card.



Electrostatic sensitive device (ESD)

- Wear working cloth and use equipment in compliance with ESD protective measures.
- Handle device with extra care.

3.3.1 EPOS4 Controllers with encased Housing

The controllers provide two extension slots (EXT1 & EXT2) located underneath the plastic lid at the housing's top face (\rightarrow Figure 3-4). The plastic lid will mechanically interlock the inserted extension card in both horizontal and vertical direction.

- EXT1 hosts the «EPOS4 EtherCAT Card».
- **EXT2** provides connectivity for advanced signal extension cards, such as for additional absolute sensors or customized signal extensions.



Continued on next page.



Figure 3-5 EPOS4 EtherCAT Card – Installation & removal



3.3.2 EPOS4 Modules

The connection of the «EPOS4 EtherCAT Card» can be established via a custom-made motherboard which defines the actual installation procedure.

Depending on the case of application (with possibly involved strong movements and high dynamic accelerations) and to guarantee failsafe operation, you might wish to consider the use of a PCIe card edge connector with retainer (\rightarrow Figure 3-6). The retainer will mechanically interlock the inserted extension card in both horizontal and vertical direction.

PCIe card edge connector EPOS4 EtherCAT Card





Setup Installation



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4 MOTHERBOARD DESIGN GUIDE

The «Motherboard Design Guide» provides helpful information on integrating the EPOS4 EtherCAT Card on a printed circuit board. It contains recommendations for the motherboard layout and specifies external components that may be required, pin assignments, and connection examples.



CAUTION

Dangerous action

Errors in implementing the design can result in serious Injury!

- Only proceed if you are skilled in electronics design!
- Designing a printed circuit board requires special skills and knowledge and may only be performed by experienced electronic developers!
- This quick guide is only intended as an aid, does not make any claim to completeness, and will not automatically result in a functional component!



Get help

If you are not trained in the design and development of printed circuit boards, you will need additional support for this point.

maxon will be happy to provide you with a quote for designing and manufacturing a motherboard for your specific application.



4.1 Schematic Overview



4.2 Requirements for Components of Third-party Suppliers

Best practice

For references and recommended components consult →Table 4-14.

4.2.1 Card Edge Connector & Socket Headers

For implementation of the «EPOS4 EtherCAT Card», a PCIe 2x18 position connector is required.

EPOS4 modules are available with two different types of socket headers.

- EPOS4 Module 24/1.5 (536630) and EPOS4 Module 50/5 (534130) feature 1.27 mm box headers.
- EPOS4 Module 50/8 (504384) and EPOS4 Module 50/15 (504383) have pin headers that permit two ways of mounting. They can either be plugged in a socket header or be directly soldered to a printed circuit board.

Find further details on the hardware in the →separate document «Hardware Reference» of the respective EPOS4 Module.





4.2.2 Supply Voltage

For voltage supply of the «EPOS4 EtherCAT Card», you may employ the EPOS4 Module's power supply. For details → separate document «Hardware Reference» of the respective EPOS4 Module.

If you intend to use another source as power supply, we recommend to connect a TVS (transient voltage suppressor) diode (D1) to the voltage supply line to protect against overvoltage resulting from voltage transients or brake energy feedback.

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4.2.3 EtherCAT Status LEDs

The «EPOS4 EtherCAT Card» provides two outputs to display the actual status and possible errors of the EtherCAT network with LEDs (D2):

- Green LED shows the RUN state
- Red LED indicates errors

LED		Description		
Green	Red	Description		
OFF	—	EPOS4 is in state INIT		
Blink	—	EPOS4 is in state PRE-OPERATIONAL		
Single flash	—	EPOS4 is in state SAFE-OPERATIONAL		
ON	—	EPOS4 is in state OPERATIONAL		
—	OFF	EPOS4 is in operating condition		
—	Double flash	An application watchdog timeout has occurred Example: Timeout of Sync Manager Watchdog		
_	Single flash	EPOS4 has changed the COM state due to an internal error Example: Change of state "Op" to "SafeOpError" due to Sync Error		
-	Blink	General Configuration Error Example: State change commanded by master is not possible due to actual settings (register, object, hardware configuration)		
Blink = continue	Blink = continuous blinking (\approx 2.5 Hz) Flash = Flashing (\approx 0.2 s), followed by pause of 1 s			

Table 4-7 EtherCAT status LEDs

The outputs are designed as open-collector circuit with internal series resistor of 150 Ohm. An external LED can be mounted as long as the current is limited to less than 20 mA with an matching series resistor (Rs).

Red/green EtherCAT status LED "sinks"		
Max. input voltage	+30 VDC	
Max. load current	20 mA	

Table 4-8 EtherCAT status LED "sinks"





EtherCAT status LED "sinks" (analogously valid for B11)



4.2.4 EtherCAT Port LEDs

The «EPOS4 EtherCAT Card» provides two outputs to display the EtherCAT port's link activity (applies for both ports, X14 "EtherCAT IN" and X15 "EtherCAT OUT"):

Green LED indicates link activity

LED Green	Description	
OFF	Port is closed	
Flicker	Port is open / activity is present	
ON	Port is open	
—	Data rate is 100 Mbit/s	
Flicker = Continuous flickering (≈10 Hz)		

Table 4-9 EtherCAT port LEDs

The outputs are designed to drive integrated LEDs of standard modular port jacks according the following specification:

Green EtherCAT port activity LED "source"		
Output voltage	U _{out} = 3.3 V - (I _{Load} x 150 Ω)	
Max. load current	10 mA	

Table 4-10 EtherCAT port activity LED "source"



Figure 4-9 EtherCAT port activity LED "source"

4.2.5 EtherCAT Connectors

The «EPOS4 EtherCAT Card» provides both transmission and receive signals for input as well as output for an EtherCAT interface. Unused connections of the EtherCAT IN/OUT connectors (pins 4, 5, 7, and 8) must be connected through to the PCIe plug-in contact.

In respect to short-term signal transmission and propagation times, sufficient short conducting paths and isolation spacing must be provided.



Wrong plugging may cause hardware damage

Even though both sockets are prepared for identical external wiring, make sure to always connect them as follows.

- Use only standard Cat5 cables with RJ45 plug, such as maxon's «Ethernet Cable» (422827).
- Use EtherCAT IN as «Input».
- Use EtherCAT OUT as «Output».

For detailed information → separate document «EPOS4 Communication Guide».



For detailed information → separate document «EPOS4 Communication Guide».



Figure 4-10 EtherCAT connector

EtherCAT	
EtherCAT Standard	IEEE 802.3 100 Base Tx
Max. bit rate	100 Mbit/s (full duplex)

Table 4-11 EtherCAT interface specification

Pin	Signal	Description
1	TX+	Transmission Data+
2	TX-	Transmission Data-
3	RX+	Receive Data+
4	ТХСТ	not applicable
5	ТХСТ	not applicable
6	RX-	Receive Data-
7	RXCT	not applicable
8	RXCT	not applicable

Table 4-12 EtherCAT connectors – Pin assignment

Continued on next page.







Table 4-13 Ethernet Cable



4.2.6 Recommended Components and Manufacturers

Recommended components		
Card Edge Connector (EXT1)	PCIe 2x18 Position, THT • Amphenol FCI (10018784-10200TLF) • Sullins Connector Solutions (NWE18DHHN-T911) • TE Connectivity (7-1734774-6)	
Retainer for Card Edge Connector (optional)	PCI express retainer • Amphenol FCI (10042618-002LF)	
EtherCAT Two Port Modular Jack (X14/X15)	 Amphenol (RJHSE-5381-02) Würth (615016137721) 	
TVS Diode (D1)	 Vishay (SMBJ54A) U_R = 54 V, U_{BR} = 60.066.3 V @ 1 mA, U_C = 87.1 V @ 6.9 A Fairchild (SMBJ54A) U_R = 54 V, U_{BR} = 60.066.3 V @ 1 mA, U_C = 87.1 V @ 6.9 A Littelfuse (SMBJ54A) U_R = 54 V, U_{BR} = 60.066.3 V @ 1 mA, U_C = 87.1 V @ 6.9 A 	
LED (D2)	Dual-sided SMT LED green/red • Lite-On (LTST-S326KGJRKT) • Dialight (597-2751-607F) • Avago (HSMF-C144)	
Decoupling (Rp/Cp)	 R/C chip combination Chip resistor 1 M Ω, 0.25 W, 500 V Chip capacitor 10 nF, 500 V 	

 Table 4-14
 Motherboard Design Guide – Recommended components



4.3 THT Footprint

Depending on your case of application and type of operation, considerable strong movements and high dynamic accelerations may occur. If the case, you might wish to consider using a PCIe card edge connector with retainer which will then mechanically interlock the inserted extension card in both horizontal and vertical direction.



Possible strong mechanical loads during operation may cause hardware damage

Operation involving strong movements and high dynamic accelerations can cause an unsecured extension card to shake loose. This can lead to serious damage of hardware or equipment and to complete failure of the system. To avoid, use a PCIe card edge connector with retainer (\Rightarrow Figure 4-11).

PCIe Card Edge Connector with Retainer



Figure 4-11 PCIe card edge connector with retainer – THT footprint [mm] – Top view

PCIe Card Edge Connector without Retainer



Figure 4-12 PCIe card edge connector – THT footprint [mm] – Top view



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CCMC | EPOS4 EtherCAT Card Hardware Reference | Edition 2019-11 | DocID rel8613

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